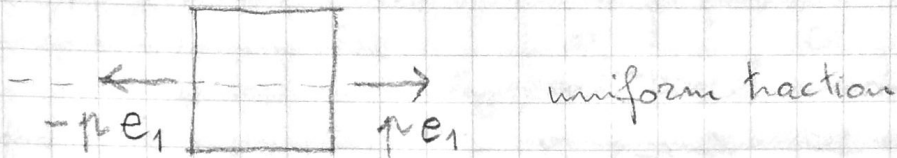


(57-58)<sub>11</sub> Monday [2014-05-05] A1.3

16:00 - 18:00

A standard problem in elasticity



cubic reference shape

let us consider "cylindrical deformations" only:

affine deformations with

$$\begin{aligned}
 F e_1 &= \lambda_1 e_1 \\
 F e_2 &= \lambda_2 e_2 \\
 F e_3 &= \lambda_3 e_3
 \end{aligned}
 \quad [F] = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix}$$

moment  
tensor

$$\begin{aligned}
 M &= \bar{l} F e_1 \otimes (p e_1) A_{F_1} \\
 &= \bar{l} \lambda_1 e_1 \otimes e_1 (p A_{F_1}) \\
 &= l_1 e_1 \otimes e_1 (p l_2 l_3) \\
 &= \underbrace{l_1 l_2 l_3 p}_{\text{current volume } V_R} e_1 \otimes e_1
 \end{aligned}$$

balance equations

$$f = 0$$

$$\text{skw } M = 0$$

$$\frac{M}{V_R} = T$$

from balance  $T = p e_1 \otimes e_1$

material characterization

$$T = \hat{T}(F) - p I + T^d$$

$\uparrow$  (incompressibility)       $\uparrow$  (dissipation)

Let us consider a compressible material with no dissipation:

$$T = \hat{T}(F)$$

with

$$[\hat{T}(F)] = \begin{pmatrix} \hat{\sigma}_{11}(F) & & \\ & \hat{\sigma}_{22}(F) & \\ & & \hat{\sigma}_{33}(F) \end{pmatrix}$$

$$[\dot{F} F^{-1}] = \begin{pmatrix} \frac{\dot{\lambda}_1}{\lambda_1} & & \\ & \frac{\dot{\lambda}_2}{\lambda_2} & \\ & & \frac{\dot{\lambda}_3}{\lambda_3} \end{pmatrix}$$

balance

$$\begin{pmatrix} \sigma_{11} & & \\ & \sigma_{22} & \\ & & \sigma_{33} \end{pmatrix} = \begin{pmatrix} p & & \\ & 0 & \\ & & 0 \end{pmatrix}$$

$$T = p e_1 \otimes e_1$$

A simple choice for  $\hat{T}(F)$  is

$$\hat{\sigma}_{11}(F) = a_1(\lambda_1 - 1)$$

$$\hat{\sigma}_{22}(F) = a_2(\lambda_2 - 1)$$

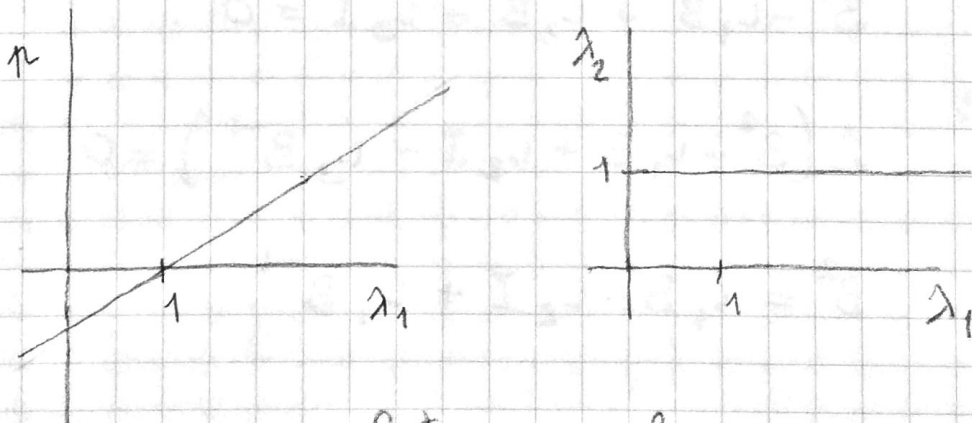
$$\hat{\sigma}_{33}(F) = a_3(\lambda_3 - 1)$$

Balance and material response

$$p = a_1(\lambda_1 - 1)$$

$$0 = a_2(\lambda_2 - 1)$$

$$0 = a_3(\lambda_3 - 1)$$



solution graphs

(59-60)<sub>11</sub> Tuesday [2014-05-06] A1.3  
9:00-11:00

The solution we derived from the assumed material response is unsatisfactory because it allows  $\lambda_1$  to be negative; further  $\lambda_2$  and  $\lambda_3$  are always equal to 1.

Let us consider the response function for a hyperelastic material  $\rightarrow (45-46)_8$

$$\hat{T}(F) = \frac{2}{\sqrt{I_3}} \left( \left( \frac{\partial \hat{\psi}}{\partial I_1} + \frac{\partial \hat{\psi}}{\partial I_2} I_1 \right) B - \frac{\partial \hat{\psi}}{\partial I_2} B^2 + \frac{\partial \hat{\psi}}{\partial I_3} I_3 I \right)$$

with  $B = FF^T$  (left Cauchy-Green tensor)

We can get a new expression by using the Cayley-Hamilton theorem stating that any tensor satisfies its characteristic equation:

$$B^3 - I_1 B^2 + I_2 B - I_3 I = 0$$

We get

$$B(B^2 - I_1 B + I_2 I - I_3 B^{-1}) = 0$$

$$B^2 = I_1 B - I_2 I + I_3 B^{-1}$$

$$\hat{T}(F) = \frac{2}{\sqrt{L_3}} \left( \frac{\partial \hat{\varphi}}{\partial u_1} B + \left( \frac{\partial \hat{\varphi}}{\partial L_3} L_3 + \frac{\partial \hat{\varphi}}{\partial L_2} L_2 \right) I - \frac{\partial \hat{\varphi}}{\partial L_2} L_3 B^{-1} \right)$$

if

$$[F] = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix}$$

then

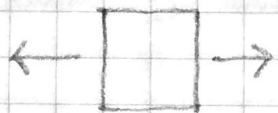
$$[B] = \begin{pmatrix} \lambda_1^2 & & \\ & \lambda_2^2 & \\ & & \lambda_3^2 \end{pmatrix}$$

(61-62)<sub>11</sub> Wednesday [2014-05-07] A1.3

9:00 - 11:00

let us consider an incompressible material.

The motion will be isochoric: any deformation is characterized by  $\det F = 1$ .



$$[F] = \begin{pmatrix} \lambda & & \\ & \frac{1}{\lambda} & \\ & & \frac{1}{\lambda} \end{pmatrix}$$

A standard strain energy for so called rubber-like material is

$$\varphi_H(F) = c_1 (I_1 - 3) \quad \text{neo-Hookean}$$

or

$$\varphi_{MR}(F) = c_1 (I_1 - 3) + c_2 (I_2 - 3)$$

Mooney-Rivlin

For the assumed deformation gradient we have

$$[C] = [F^T F] = \begin{pmatrix} \lambda^2 & & \\ & \frac{1}{\lambda} & \\ & & \frac{1}{\lambda} \end{pmatrix}$$

$$I_1 = \text{tr } C = \lambda^2 + \frac{2}{\lambda}$$

$$[C^2] = \begin{pmatrix} \lambda^4 & & \\ & \frac{1}{\lambda^2} & \\ & & \frac{1}{\lambda^2} \end{pmatrix}$$

$$v_2 = \frac{1}{2} \left( (\text{tr } C)^2 - \text{tr } C^2 \right) = \frac{1}{2} \left( \lambda^4 + 4\lambda + \frac{4}{\lambda^2} - \lambda^4 - \frac{2}{\lambda^2} \right) = 2\lambda + \frac{1}{\lambda^2}$$

$$v_3 = 1$$

$$[\dot{F}] = \begin{pmatrix} \dot{\lambda} & & \\ & -\frac{1}{2} \lambda^{-\frac{3}{2}} \dot{\lambda} & \\ & & -\frac{1}{2} \lambda^{-\frac{3}{2}} \dot{\lambda} \end{pmatrix}$$

$$[\dot{F} F^{-1}] = \begin{pmatrix} \frac{\dot{\lambda}}{\lambda} & & \\ & -\frac{1}{2} \lambda^{-\frac{3}{2}} \dot{\lambda} \lambda^{-\frac{1}{2}} & \\ & & -\frac{1}{2} \lambda^{-\frac{3}{2}} \dot{\lambda} \lambda^{-\frac{1}{2}} \end{pmatrix}$$

$$[\dot{F} F^{-1}] = \begin{pmatrix} 1 & & \\ & -\frac{1}{2} & \\ & & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} \dot{\lambda} \\ \lambda \end{pmatrix}$$

note  $\text{tr } \dot{F} F^{-1} = 0$