

[2016-05-10]

External dissipation and stability

(balance)

$$\text{skw } M - M^{\dagger} = 0$$

$$M^{\dagger} \cdot W \geq 0 \quad (\text{dissipation inequality})$$

$$M^{\dagger} = \eta W \Rightarrow \eta W \cdot W \geq 0 \Rightarrow \eta \geq 0$$

$$\text{skw } M - \eta W = 0 \quad (\text{balance})$$

$$\frac{\sqrt{2}}{4} \mu V_{\text{sk}} (\cos \vartheta - \sin \vartheta) e_2 \otimes e_1 - \eta \dot{\vartheta} e_2 \otimes e_1 = 0$$

$$\mu \frac{\sqrt{2}}{4} V_{\text{sk}} (\cos \vartheta - \sin \vartheta) = \eta \dot{\vartheta} \quad (\cos \vartheta - \sin \vartheta) = -\sqrt{2} \sin \left(\vartheta - \frac{\pi}{4} \right)$$

linearization

$$\cos \vartheta = \cos \vartheta_0 - \sin \vartheta_0 (\vartheta - \vartheta_0) + \dots$$

$$\vartheta_0 = \frac{\pi}{4}$$

$$\sin \vartheta = \sin \vartheta_0 + \cos \vartheta_0 (\vartheta - \vartheta_0) + \dots$$

$$\cos \vartheta_0 = \sqrt{2} \sin \vartheta_0$$

$$\cos \vartheta - \sin \vartheta = 0 - \sqrt{2} (\vartheta - \vartheta_0) + \dots$$

$$-\mu \frac{\sqrt{2}}{4} V_{\text{sk}} \sqrt{2} (\vartheta - \vartheta_0) = \eta \dot{\vartheta} \quad \text{linearized equation}$$

$$-\alpha (\vartheta - \vartheta_0) = \eta \dot{\vartheta} \quad (-\alpha \tilde{\vartheta} = \eta \dot{\tilde{\vartheta}})$$

$$\left. \begin{aligned} (\vartheta - \vartheta_0) &= \tilde{\vartheta}_0 e^{-\frac{\alpha}{\eta} t} \\ \Rightarrow \dot{\vartheta} &= -\frac{\alpha}{\eta} \tilde{\vartheta}_0 e^{-\frac{\alpha}{\eta} t} \\ \theta(0) - \vartheta_0 &= \tilde{\vartheta}_0 \\ \Rightarrow \dot{\vartheta} &= -\frac{\alpha}{\eta} (\vartheta - \vartheta_0) \end{aligned} \right\}$$

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$$\theta(t) = \theta_0 + \tilde{\theta}_0 e^{-\frac{\alpha}{\eta} t}$$

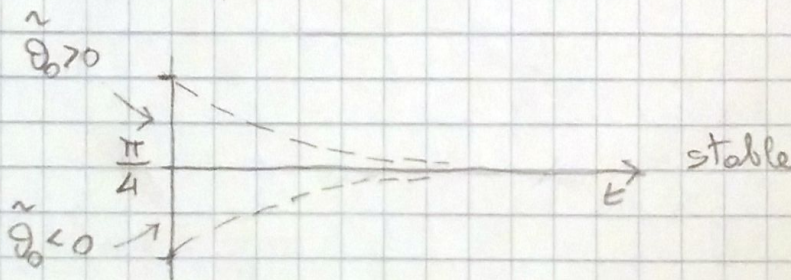
$$-\mu \frac{1}{2} V_R \sin\left(\theta - \frac{\pi}{4}\right) = \eta \dot{\theta}$$

linearization around $\theta_0 = \frac{\pi}{4}$

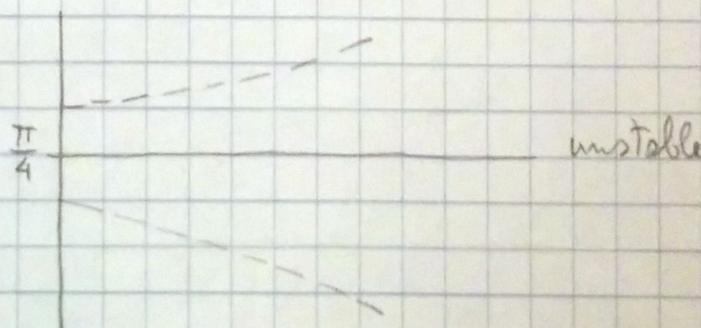
$$-\underbrace{\mu \frac{1}{2} V_R}_{\alpha} \left(\theta - \frac{\pi}{4}\right) = \eta \dot{\theta}$$

$$-\alpha \tilde{\theta}_0 e^{-\frac{\alpha}{\eta} t} = \eta \left(-\frac{\alpha}{\eta}\right) \tilde{\theta}_0 e^{-\frac{\alpha}{\eta} t}$$

$$\mu > 0 \Leftrightarrow \alpha > 0$$



$$\mu < 0 \Leftrightarrow \alpha < 0$$



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linearization around

$$\theta_0 = \frac{\pi}{4} + \pi = \frac{5}{4}\pi$$

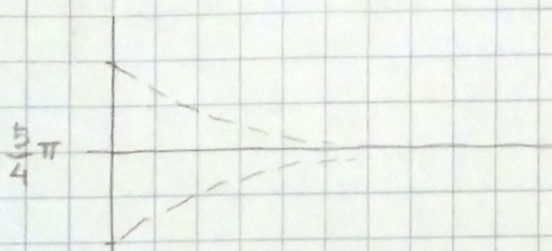
$$\begin{aligned} \sin\left(\theta - \frac{\pi}{4}\right) &= \sin\left(\theta_0 - \frac{\pi}{4}\right) + \cos\left(\theta_0 - \frac{\pi}{4}\right)(\theta - \theta_0) + \dots \\ &= \sin(\pi) + \cos(\pi)(\theta - \theta_0) + \dots \\ &= -(\theta - \theta_0) \end{aligned}$$

$$\cos\theta - \sin\theta = -\sqrt{2} \sin\left(\theta - \frac{\pi}{4}\right) = +\sqrt{2} \left(\theta - \frac{5}{4}\pi\right) + \dots$$

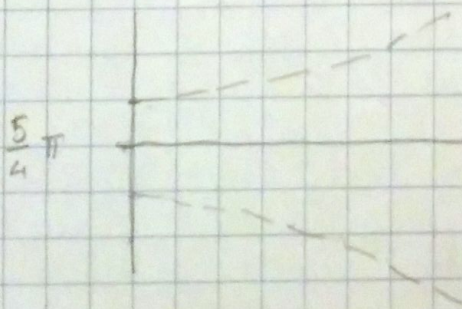
$$\mu \frac{1}{2} V_E (\theta - \theta_0) = \gamma \dot{\theta} \quad \alpha (\theta - \theta_0) = \gamma \dot{\theta}$$

$$\theta(t) = \frac{5}{4}\pi + \tilde{\theta}_0 e^{\frac{\alpha}{\gamma} t}$$

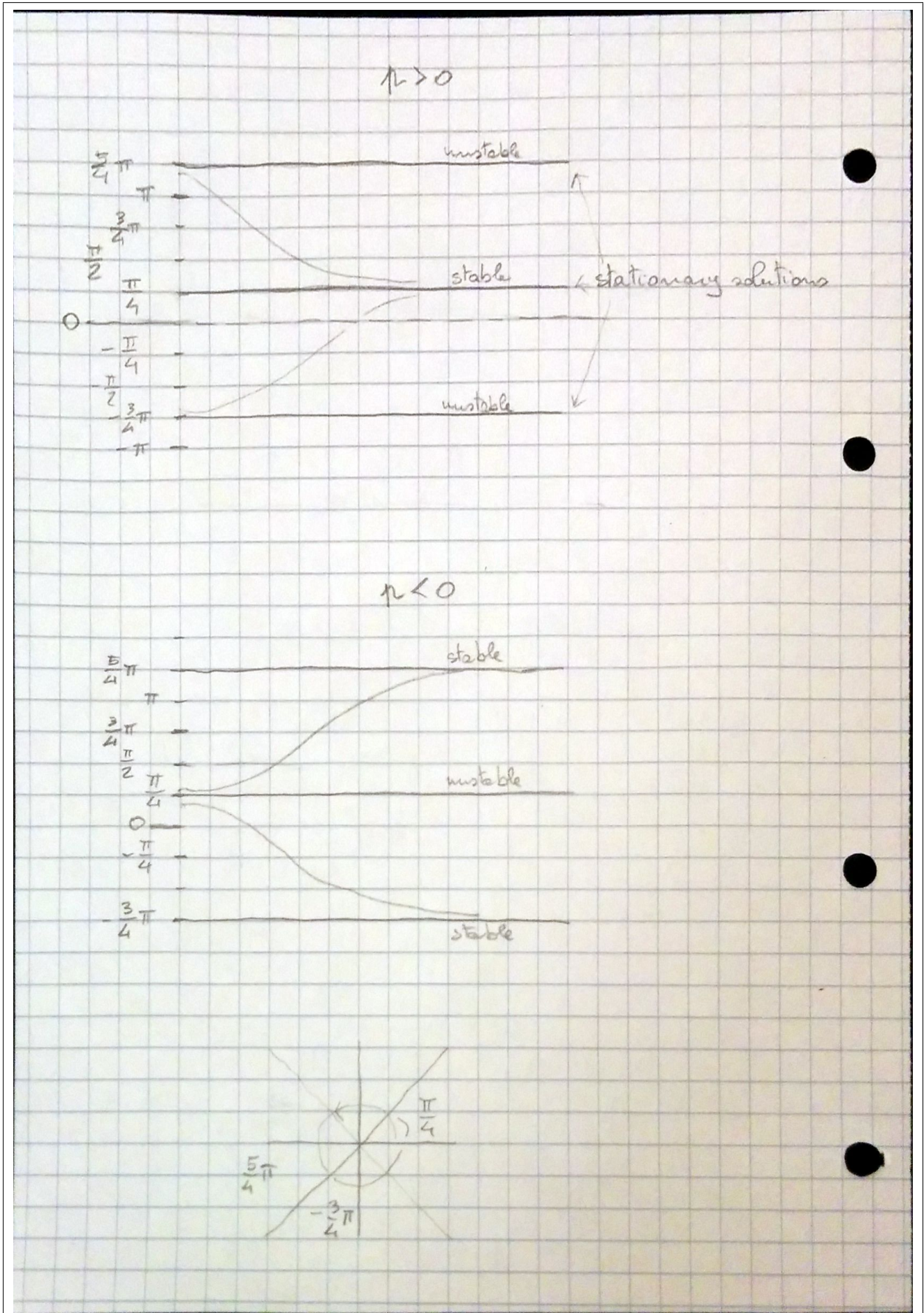
$$\mu < 0 \Leftrightarrow \alpha < 0$$



$$\mu > 0 \Leftrightarrow \alpha > 0$$



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Potential energy

$$\begin{aligned} & \text{skw } M \cdot \text{skw } \dot{\theta} \\ &= \frac{\sqrt{2}}{2} \mu V_R (\cos \theta - \sin \theta) \dot{\theta} \end{aligned}$$

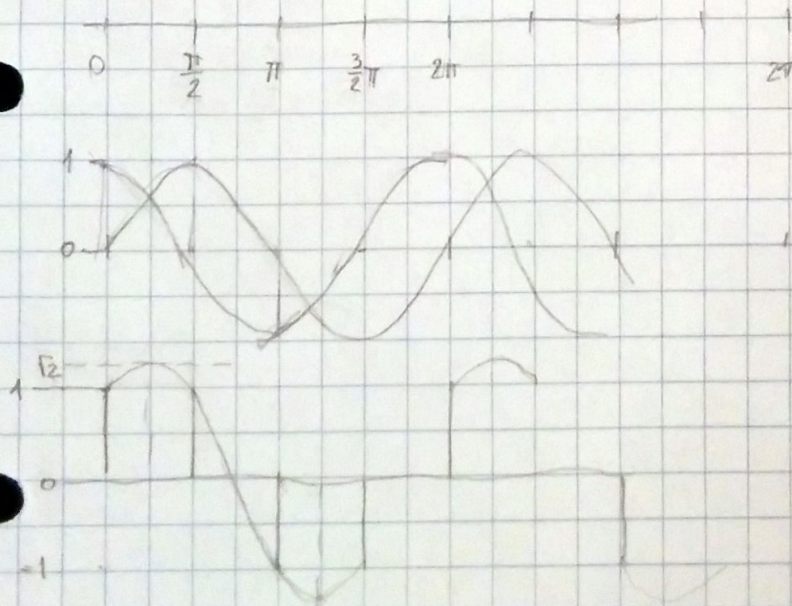
This is the power of the external force distribution, ^(just the skewsymmetric part?)

Is there any potential?

$$\frac{\sqrt{2}}{2} \mu V_R (\cos \theta - \sin \theta) \dot{\theta} = \frac{d}{dt} \frac{\sqrt{2}}{2} \mu V_R (\sin \theta + \cos \theta)$$

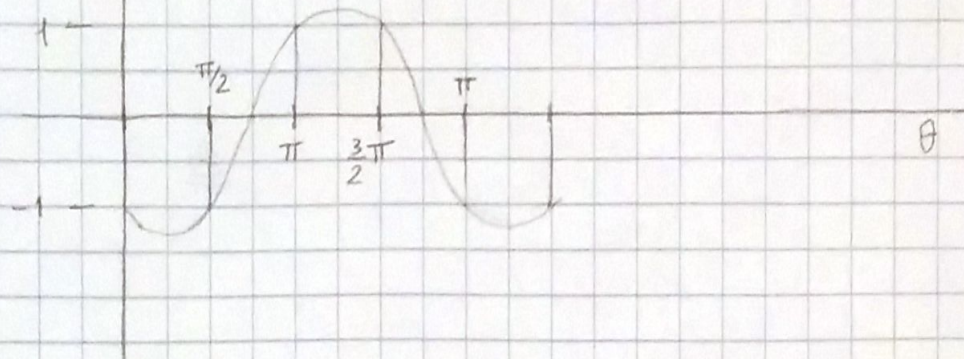
$$\cos \theta \dot{\theta} = \frac{d}{dt} \sin \theta \quad ; \quad -\sin \theta \dot{\theta} = \frac{d}{dt} \cos \theta$$

We define conventionally the "potential energy" as the opposite of that expression



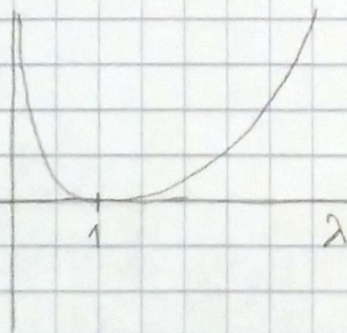
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The graph of the potential energy turns out to be



According to the previous stability analysis the minima of this graph denote stable shapes, while maxima denote unstable shapes.

The strain energy, as a function of λ , is described by the graph



$$\varphi(\lambda) = c \left(\lambda^2 + \frac{2}{\lambda} - 3 \right)$$

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