

[2016-05-23]

Linear elasticity (small deformations)

$$F(\boldsymbol{\varepsilon}) = \mathbf{I} + \mathbf{E}(\boldsymbol{\varepsilon}) + \mathbf{H}(\boldsymbol{\varepsilon}) + o(\boldsymbol{\varepsilon})$$

$$F(\boldsymbol{\varepsilon}) = \mathbf{R}(\boldsymbol{\varepsilon})\mathbf{U}(\boldsymbol{\varepsilon})$$

$$\mathbf{R}(\boldsymbol{\varepsilon}) = \mathbf{R}(\mathbf{0}) + \left. \frac{d}{d\boldsymbol{\varepsilon}} \mathbf{R} \right|_{\boldsymbol{\varepsilon}=\mathbf{0}} \boldsymbol{\varepsilon} = \mathbf{I} + \mathbf{H} + o(\boldsymbol{\varepsilon})$$

$$\mathbf{U}(\boldsymbol{\varepsilon}) = \mathbf{U}(\mathbf{0}) + \left. \frac{d}{d\boldsymbol{\varepsilon}} \mathbf{U} \right|_{\boldsymbol{\varepsilon}=\mathbf{0}} \boldsymbol{\varepsilon} = \mathbf{I} + \mathbf{E} + o(\boldsymbol{\varepsilon})$$

$$\mathbf{R}(\boldsymbol{\varepsilon})^T \mathbf{R}(\boldsymbol{\varepsilon}) = \mathbf{I} \Rightarrow (\mathbf{I} + \mathbf{H}^T)(\mathbf{I} + \mathbf{H}) = \mathbf{I}$$

$$\mathbf{I} + \mathbf{H} + \mathbf{H}^T + o(\boldsymbol{\varepsilon}) = \mathbf{I}$$

$$\Rightarrow \mathbf{H} + \mathbf{H}^T = \mathbf{0}$$

$$\mathbf{U}(\boldsymbol{\varepsilon}) = \mathbf{U}(\boldsymbol{\varepsilon})^T \Rightarrow \mathbf{I} + \mathbf{E} = \mathbf{I} + \mathbf{E}^T$$

$$\Rightarrow \mathbf{E} = \mathbf{E}^T$$

\mathbf{H} infinitesimal rotation

\mathbf{E} infinitesimal strain

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$$\begin{aligned}
 F^T F &= (I + E^T + \Theta^T)(I + E + \Theta) \\
 &= I + E + \Theta + E^T + \Theta^T = I + 2E + o(\epsilon)
 \end{aligned}$$

$$I_1 = 3 + 2 \operatorname{tr} E + o(\epsilon)$$

$$\begin{aligned}
 \det F &= 1 + \left(\frac{d}{d\epsilon} \det F(\epsilon) \right) \epsilon + o(\epsilon) \\
 &= 1 + \operatorname{tr} E + \operatorname{tr} \Theta + o(\epsilon) \\
 &= 1 + \operatorname{tr} E + o(\epsilon)
 \end{aligned}$$

Isotropic elastic (compressible neo-Hookean) material

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$$\hat{T}(F) = 2k_I J^{-\frac{5}{3}} \left(B - \frac{1}{3} L_1 I \right) + 2k_V (J-1) I$$

$$B - \frac{1}{3} L_1 I = I + 2E - \frac{1}{3} (3 + 2 \operatorname{tr} E) I + o(\varepsilon)$$

$$= I + 2E - I - \frac{2}{3} (\operatorname{tr} E) I + o(\varepsilon)$$

$$= 2 \left(E - \frac{1}{3} (\operatorname{tr} E) I \right) + o(\varepsilon)$$

$$J^{-\frac{5}{3}} = 1 - \frac{5}{3} \left(\frac{d}{d\varepsilon} \det F(\varepsilon) \right) \varepsilon + o(\varepsilon) = 1 - \frac{5}{3} \operatorname{tr} E + o(\varepsilon)$$

$$J^{-\frac{5}{3}} \left(B - \frac{1}{3} L_1 I \right) = 2 \left(E - \frac{1}{3} (\operatorname{tr} E) I \right) + o(\varepsilon)$$

$$\hat{T}(F) = 4k_I \left(E - \frac{1}{3} (\operatorname{tr} E) I \right) + 2k_V (\operatorname{tr} E) I$$

$$= \left(2k_V - \frac{4}{3} k_I \right) (\operatorname{tr} E) I + 4k_I E$$

$$= \underbrace{\left(\kappa - \frac{2}{3} \mu_L \right)}_{\lambda_L} (\operatorname{tr} E) I + 2\mu_L E$$

$$= \lambda_L (\operatorname{tr} E) I + 2\mu_L E \quad (\text{Lamé})$$

$$\kappa - \frac{2}{3} \mu_L = \lambda_L \Rightarrow \kappa = \lambda_L + \frac{2}{3} \mu_L = \frac{1}{3} (3\lambda_L + 2\mu_L)$$

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Linear elasticity

isotropic material

$$\hat{T}(F) = \lambda_L (\text{tr} E) I + 2\mu_L E$$

 λ_L, μ_L Lamé moduli $\mu_L = 2k_s$ shear modulus $\kappa = 2k_v$ bulk modulus

$$\lambda_L = \kappa - \frac{2}{3}\mu_L$$

From uniaxial deformation (linearized)

Uniaxial deformation

$$[F] = J^{\frac{1}{3}} \begin{pmatrix} \lambda & & \\ & \frac{1}{\sqrt{\lambda}} & \\ & & \frac{1}{\sqrt{\lambda}} \end{pmatrix} = \begin{pmatrix} \lambda_a & & \\ & \lambda_r & \\ & & \lambda_r \end{pmatrix}$$

$$\begin{cases} \lambda_a = \lambda J^{\frac{1}{3}} \\ \lambda_r = \frac{1}{\sqrt{\lambda}} J^{\frac{1}{3}} \end{cases} \Rightarrow \begin{cases} \frac{\lambda_a}{\lambda_r} = \lambda \sqrt{\lambda} \Rightarrow \lambda = \left(\frac{\lambda_a}{\lambda_r} \right)^{\frac{2}{3}} \\ J = \lambda_a \lambda_r^2 \end{cases}$$

$$[III] \begin{cases} \frac{\mu}{k_I} = 2J \left(\lambda^2 - \frac{1}{\lambda} \right) \\ \frac{\mu}{k_V} = 6(J-1) \end{cases}$$

$$\lambda_a = 1 + \varepsilon_a, \quad \lambda_r = 1 + \varepsilon_r$$

$$J = 1 + \varepsilon_a + 2\varepsilon_r \quad (\text{small strains})$$

$$\lambda = 1 + \frac{2}{3}(\varepsilon_a - \varepsilon_r)$$

$$2J\left(\lambda^2 - \frac{1}{\lambda}\right) = 0 + 2(2+1)\frac{2}{3}(\varepsilon_a - \varepsilon_r)$$

$$= 4(\varepsilon_a - \varepsilon_r)$$

$$\left\{ \begin{array}{l} \frac{F}{2k_I} = 2(\varepsilon_a - \varepsilon_r) \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{F}{2k_V} = 3(2\varepsilon_r + \varepsilon_a) \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{F}{M_L} = 2(\varepsilon_a - \varepsilon_r) \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{F}{K} = 3(2\varepsilon_r + \varepsilon_a) \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{F}{2M_L} = \varepsilon_a - \varepsilon_r \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{F}{3K} = \varepsilon_a + 2\varepsilon_r \end{array} \right.$$

$$F\left(\frac{1}{M_L} + \frac{1}{3K}\right) = 3\varepsilon_r$$

$$F\left(-\frac{1}{2M_L} + \frac{1}{3K}\right) = 3\varepsilon_r$$

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$$k = \lambda_L + \frac{2}{3}\mu_L = \frac{1}{3}(3\lambda_L + 2\mu_L)$$

$$\nu = 3 \frac{3\mu_L k}{3k + \mu_L} \varepsilon_a$$

$$= 3 \frac{\mu_L (3\lambda_L + 2\mu_L)}{3\lambda_L + 2\mu_L + \mu_L} \varepsilon_a$$

$$= \frac{\mu_L (3\lambda_L + 2\mu_L)}{\lambda_L + \mu_L} \varepsilon_a$$

$\underbrace{\hspace{10em}}_Y$
Young's modulus

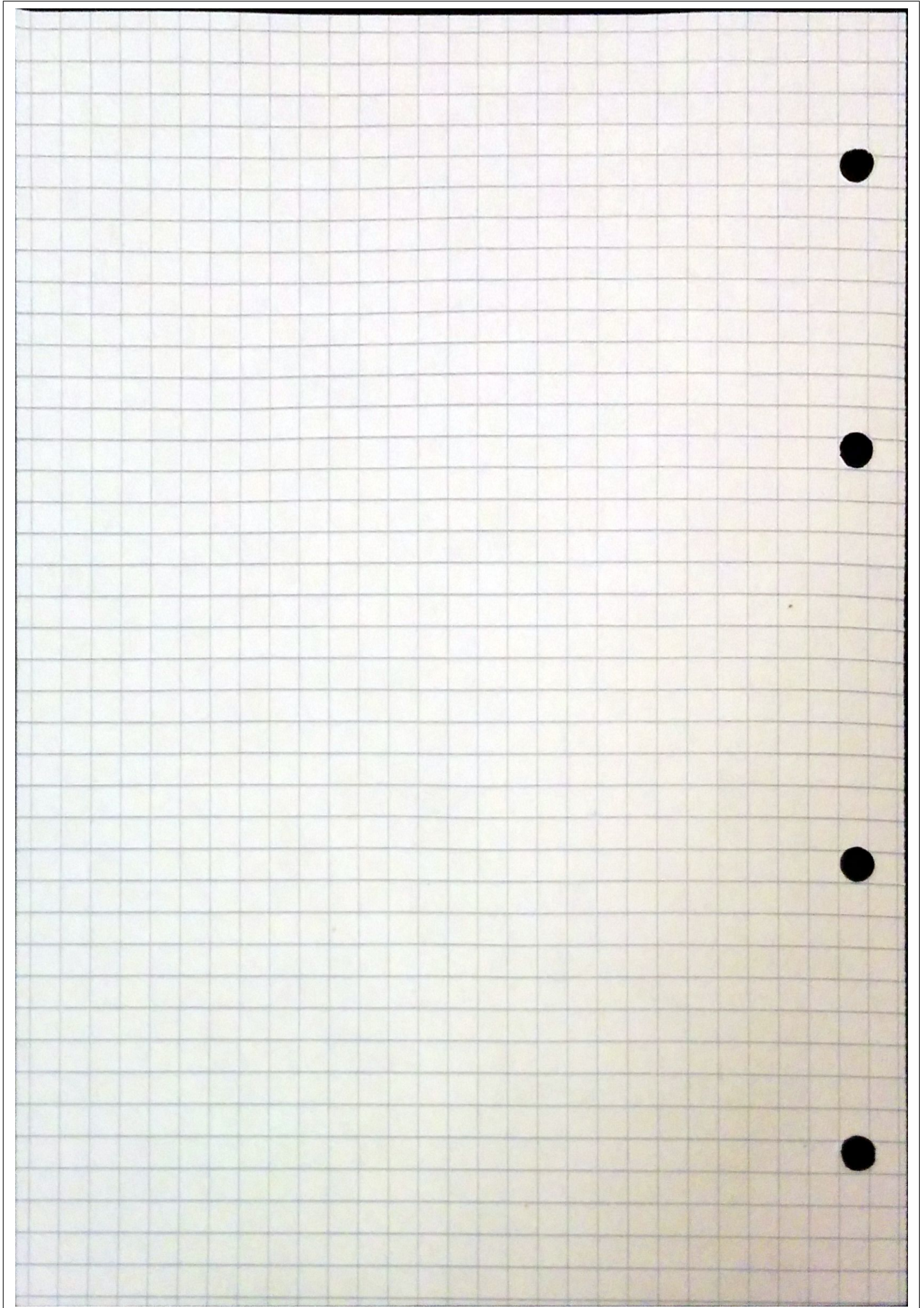
$$\frac{\varepsilon_r}{\varepsilon_a} = \frac{-3k + 2\mu_L}{6\mu_L k} \frac{3\mu_L k}{3k + \mu_L}$$

$$= \frac{-3\lambda_L - 2\mu_L + 2\mu_L}{2(3\lambda_L + 2\mu_L + \mu_L)}$$

$$= -\frac{\lambda_L}{2(\lambda_L + \mu_L)}$$

$\underbrace{\hspace{10em}}$
Poisson's ratio

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